





EINSTAR

V1.0.6

User Manual

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Overview Disclaimer

Safety instructions

Signal	Meaning
Ê	This symbol is used to inform you of the additional information of the product.
	This symbol is used to inform you of incorrect operations that may damage the device or result in data loss. Any damages resulting from misuse are not covered by the warranty.
A	This symbol is used to inform you of the potential risks that may result in serious personal injury and other safety incidents.

Compliance

Symbol	Description
CE	LVD/EMC Directive This product complies with the European Low Voltage Directive 2014/35/EU and EMC Directive 2014/30/EU.
	WEEE Directive-2012/19/EU The product this manual refers to is covered by the Waste Electrical & Electronic Equipment (WEEE) Directive and must be disposed of in a responsible manner.
Class 1 Laser Product	This device complies with "IEC 60825-1:2014 Safety of laser products Part 1: Equipment classification and requirements". Wavelength:940nm Pulse width:9ms Maximum light power:0.7W
UK CA	The UKCA marking is the product marking used for products being placed on the market in Great Britain(England, Scotland and Walse).

About this document

This document is related to your safety, lawful rights and responsibilities. Read it carefully before installing and using the product.

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- In the event of any ambiguity and/or any advice on the contents of the document, contact us by the contact info in this document.

For more information, please visit our support website: support.einstar.com (https://support.einstar.com (support.einstar.com (support.einstar.com ((support.einstar.com"/>support.einstar.com ((support.einstar.com (support.einstar.com (support.einstar.com"/>support.einstar.com (<a hre

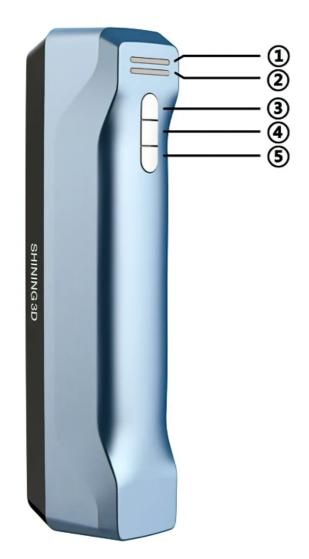
Device

Please read carefully before the first time of using Einstar (hereinafter referred to as the "Scanner").

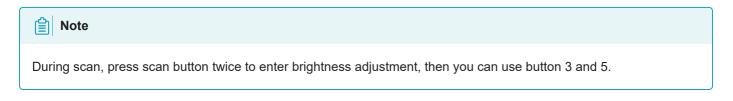
Appearance

Scanner

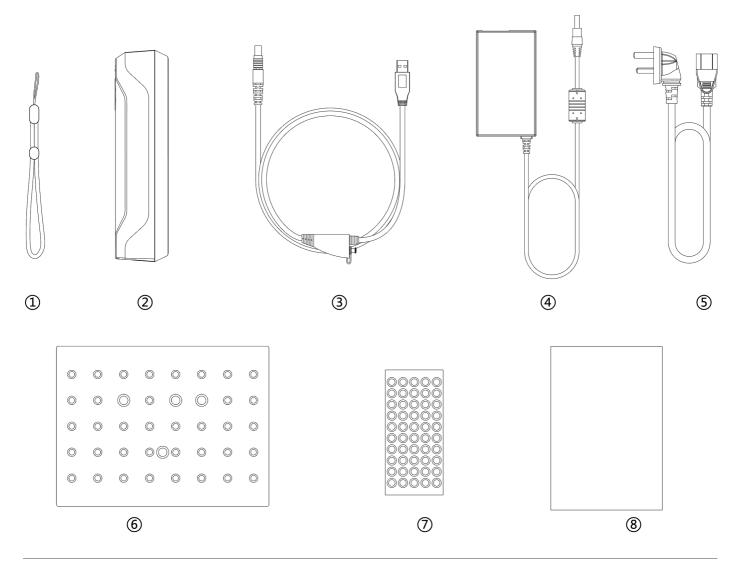




Appearance	Description
1	Working distance indicator
2	Scanner status indicator
3	Zoom in/Brighter
4	Preview/Scan/Pause
5	Zoom out/Darker

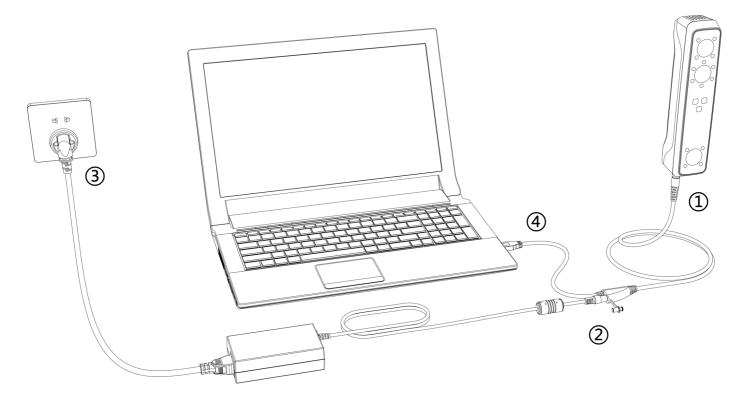


Component



Components	Description
1	wrist strap
2	scanner body
3	USB cable
4	power adapter 12V/5A
5	power cable
6	calibration board
7	markers
8	quick start guide

Connect the cable

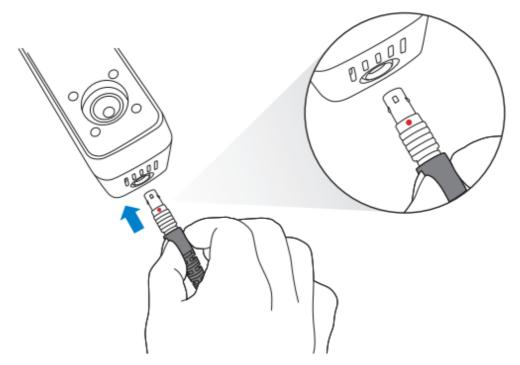


🔨 Warning

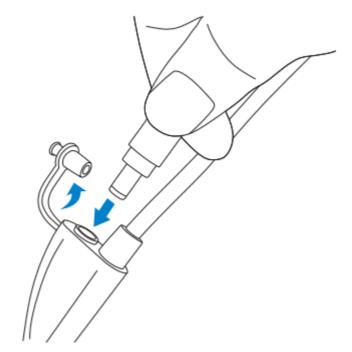
Make sure you are using the correct power adapter (12V/5A). Please install the software before using the device.

Steps

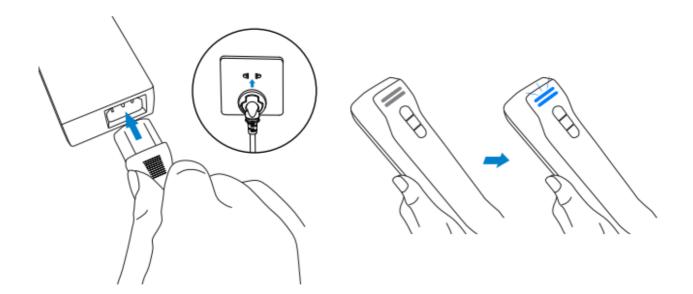
1. Plug USB cable into the bottom of Scanner, the red dot should be consistent with the front side of the scanner.



2. Plug the power cable into the USB cable.



3. Power on and the LED indicator should show blue.



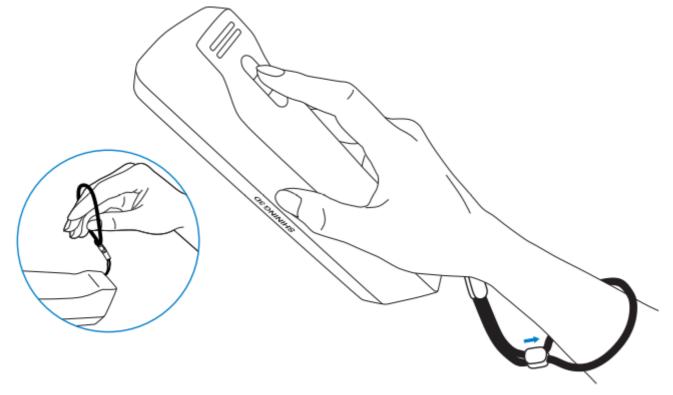
4. Plug the other side of USB cable into the USB port of computer.

Now you can see our device in your Device Manager.

~	ď.		
	>		Audio inputs and outputs
	>	\$	Batteries
	>	翕	Biometric devices
	>	*	Bluetooth
	>	Q	Cameras
	>	-	Computer
	>	-	Disk drives
	>	101	Display adapters
	>	\square	Firmware
	>	PHO	Human Interface Devices
	>	-	IDE ATA/ATAPI controllers
	>		Keyboards
	>		Memory technology devices
	>	U	Mice and other pointing devices
	>		Monitors
	>	-	Network adapters
	>		Print queues
	>		Processors
	~	-	Shining3D
	L	_	🖵 Einstar
	>		Software components
	>	•	Software devices

Hold the scanner

Put on and tighten the wrist strap. Hold the scanner securely as shown in the picture.



Install software

To use the scanner, you need to install the EXStar software first (hereinafter referred to as the "software").

Computer & Operating system requirement

Recommended computer:

Component	Model
CPU	Intel [®] Core™ i7-11800H or above
Graphics card	NVIDIA GTX 1060 or above
Graphics memory	6GB or above
RAM	32GB or above
USB	2.0 or above

Recommended operating system: Windows 10, Windows 11 (both 64-bit only)

CPU

Improper computer configuration or hardware issues will cause CPU performance degradation and affect the user experience, it is recommended to use the CPU-Z tool to check CPU performance before starting scanning.

CPU-Z: https://www.cpuid.com/softwares/cpu-z.html (https://www.cpuid.com/softwares/cpu-z.html)

Install and launch CPU-Z, follow the steps in below figure to get a CPU multi thread performance score. A score of **4000** or more is required.

👜 CPU-Z	_		×
CPU Mainboard Memory SPD Graphics CPU Single Thread	Bench A	bout	
This Processor 547.8 Reference			
CPU Multi Thread	-		
This Processor 5093.1			
Threads 16 Multi Thread	Ratio	9.30	
Benchmark Version 17.01.64			•
Bench CPU Stress CPU Stress CPU	Submit and	d Compare	·
This Processor 11th Gen Intel?Core?i7-118	300H @ 2.	30GHz	
Reference <please select=""></please>			•
CPU-Z Ver. 2.01.0.x64 Tools -	Validate	C	ose

OpenGL

To use the scanner, you need a graphics card (integrated or discrete) which can support **OpenGL4.3** or above.

Use OpenGL Extensions Viewer (https://realtech-vr.com/home/glview) to check the OpenGL version, if it's lower than 4.3, please update the graphics card driver and check again, If it's still lower than 4.3, it means that the graphic card CAN NOT support the scanner.

🕎 OpenGL Extensions Viewer - (6.3.7 . 0				_		×
🏫 🕁 🎫 Renderer:	NVIDIA GeForce	RTX 3060 Laptop GPU/PCIe/S	SE2 (Forward Conte 👻 🧮 Da	atabase: OpenGL.org		*	
Tasks Summary Extensions	View b system info		oout your graphics rer	nderer			
Display modes & pixel format GL Rendering tests Vulkan Rendering tests	s	Renderer:Adapter RAM:	NVIDIA GeForce RTX 3060 L 6144 MB	Laptoj	GRAPHICS	S BY	
Database OpenGL Report Vulkan Report CPU Report		 Monitors: Resolution: Operation system: 	Generic PnP Monitor Microsoft Windows 11 家庭	 中文	NVIDI	A.	
Submit Report Technical Support	OpenGL	Processor:	11th Gen Intel(R) Core(TM)	See details			
		💐 Version:	4.6 4.6.0 NVIDIA 472.56	See details			
	DirectX	Oriver version:	Geforce [™] Drivers 472.56 11-3-2021 Version94.6.1f.0.1f	Check for update	ed drivers		
		Supported profiles:	12.1, 11.4	Get the latest ver	rsion		
	Vulkan _	Shader model:	5.0, 4.1				
See also Find OpenGL drivers Check for updates		O Version:	1.2.175	Get Vulkan			
About Get version for Android D iOS D macOS	A	1	ideo card. Click 'Get the latest versi				
Ready	A more updated	display drivers exists for your v	ideo card. Click Get the latest Versi	on.			

GPU

It is highly recommend to use a NVIDIA¹ discrete graphics card for the scanner.

The NVIDIA discrete graphics card should support **CUDA10.2** or above.

Use **NVIDIA Control Panel** to get the CUDA version with follow steps.

- Launch NVIDIA Control Panel
- Go to Help>>System information>>Components.

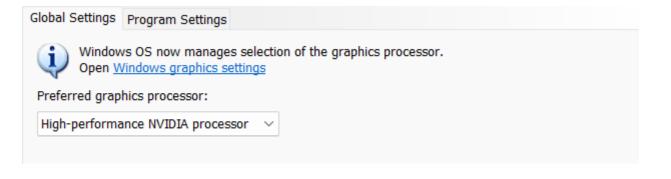
File Name	File Version	Product Name	
	File Version	Floduce Name	i i
3D Settings	07.01.14.0100		
s nvGameS.dll	27.21.14.6192	NVIDIA 3D Settings Server	
🕹 nvGameSR.dll		NVIDIA 3D Settings Server	
SINCUDA64.DLL		NVIDIA CUDA 11.2.162 driver	
🐸 PhysX	09.19.0218	NVIDIA PhysX	
Display			_
🜖 nvDispS.dll	27.21.14.6192	NVIDIA Display Server	
🜖 nvDispSR.dll	27.21.14.6192	NVIDIA Display Server	
Developer			
) nvDevToolS.dll	27.21.14.6192	NVIDIA 3D Settings Server	
i) nvDevToolSR.dll	27.21.14.6192	NVIDIA Licensing Server	
Licensing			
	014140100		
nvLicensingS.dll	6.14.14.6192	NVIDIA Licensing Server	
Video			
nvViTvS.dll	27.21.14.6192	NVIDIA Video Server	~

Use a discrete graphics card on desktop

• Connect your monitor to the port of discrete graphics card on the back of your computer, OS will use the discrete graphics card automatically.

Use a discrete graphics card on laptop

- Launch NVIDIA Control Panel on your laptop.
- In 3D Settings --> Manage 3D Settings --> Global Settings, select High-performance NVIDIA processor and Apply.



Get the installation package

Please visit the following website to get the installation package. https://support.einstar.com/support/home (https://support.einstar.com/support/home)

Install the software

Please follow the installation wizard to install the software.

Solution Note	
 Administrator rights are required for the installation of the software. Please do not install the software in C:\Program Files or C:\Program Files (x86). The software will not run when installed under these folders due to restricted rights. 	

1. We use CUDA from NVIDIA to get high scanning experience. ←

Activate the device

Note

You need a Shining 3D User Account before activating the device.

Register for Shining 3D User Account

For new user, you need to register a Shining 3D User Account first, click **Register** in the pop-up window when launching EXStar, or click **Sign Up** in our Shining 3D User Account website: https://passport.shining3d.com/ (https://passport.shining3d.com/login?redirect=%2F)

+1 United	States	Ŧ
State/region	do not support modification a please choose cautiously	fter submissio
Enter pho	ne number or email	
0	Click the button to start	verification
Please en	ter the verification code	Send Code
Please en	ter your name	
Enter at le	east 6 characters password	i

Note

- You need to enter valid email or phone number to get verify code for registration.
- Please enter correct user information for better service.
- Please read and then check Privacy Policy (Mandatory).

Log in Shining 3D User Account

Log in Shining 3D User Account from the pop-up window when launching EXStar.

If your computer failed to connect to the network:

•Check the network connection and click **Refresh** to reconnect to the network. It will jump back to the login interface after successfully connecting to the network.

•If your computer can not connect to the network successfully, click **offline activation** to directly perform the offline activation.

User Account	Network Not Available
Shining 3D User Account	Shining 3D User Account 🛛 🗙
Use Password Use VerifyCode	
● + 86 中国 China ●	
Input phone number or E-mail	
Input password	Failed to connect to network. Check the network.
I have read and accepted Forgot password? Privacy policy	Refresh
Login	If there is any issue with the network, please perform an offline activation .
Register Guest Mode Contact Us	Guest Mode Contact Us

Activate the device

Online activation

If the computer is connected to the Internet, the activation will be processed automatically after you login Shining 3D User Account.

Offline activation

You need another computer which is connected to Internet to help you finish the offline activation.

Click offline activation to enter the activation wizard.

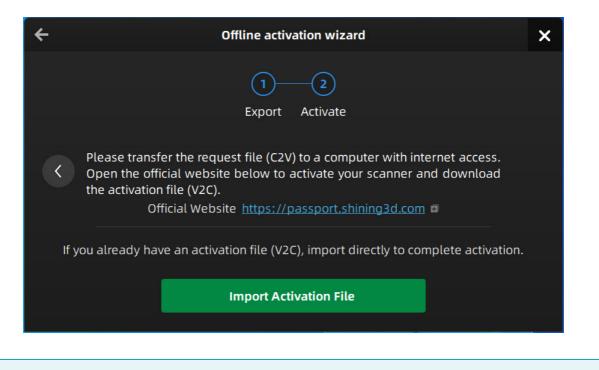
1.Connect scanner to the computer with no network, export C2V file.

÷	Offline activation wizard	×
	1 2 Export Activate	
	ir request file (C2V). ed request file is only for this scanner.	
	Export Request File	

2.Copy the C2V file to the other computer which is connected to Internet.

3.On the computer with network, login https://passport.shining3d.com/ (https://passport.shining3d.com/login? redirect=%2F), upload your C2V file in offline activation page, complete the information then click Activate button to go to download page.

4.Copy the V2C file to the computer with no network, import the file into the software.



Note

If you fail to activate the device in neither way, please contact your supplier or our support team (https://support.einstar.com/).

Upgrade

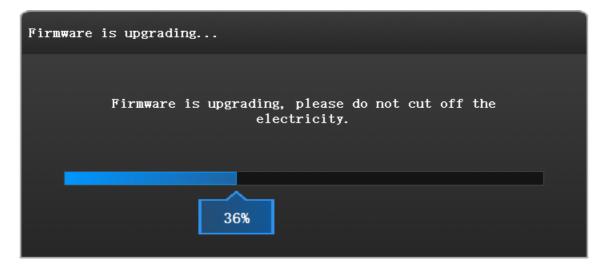
When new software is released, you will get prompted when launching the software. If the firmware in the software is newer than that in the scanner, you will get prompted too.

Firmware upgrade

The firmware is running on the scanner, it will be upgraded for better performance, stability or bug fixing.

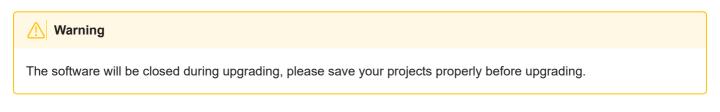


When the scanner is connected, the software will automatically detect the firmware. If the firmware does not match, it will prompt you to upgrade the firmware. Click **Yes** to upgrade.



Software upgrade

Software upgrade is to optimize software performance, add new functions or bug fixing.



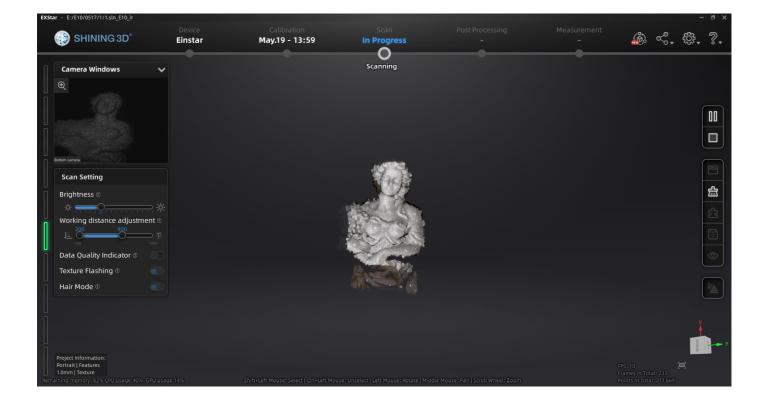
It is highly recommended to use the latest version of software. If not, a reminder will pop up immediately when you launch the software.

Update Reminder		
Update information:		
Download now	Remind me later	

Click **Download Now** will download the new installation package in the background, you can continue using the software. Please do not close the software before the download has finished. Once it finished, the following prompt will show.

Warning		
A new version has been detected,install now?		
Yes	No	

Click Yes to start the installation of the new version.



Navigation bar

Device	Calibration	Scan	Post Processing	Measurement
Einstar	May.09 - 09:25	In Progress		-
		Q		
		Scanning		12-46-32-49-116-4

Navigation	Description
Device	Displays the device status: online / offline
Calibration	Click to start calibration.
Scan	Into scan process.
Post Processing	Into post processing after generating the point cloud, includes mesh and mesh editing.
Measurement	Use the software to measure your model.

Settings and feedback



Social

Function	Description
Official Website	Open the official website (https://www.einscan.com/) of Shining 3D to learn about the company's products and information.
Facebook	Enter Shining 3D's Facebook (https://www.facebook.com/groups/einscan) to view product introduction and other operations.
Support Platform	Enter Shining 3D's support platform (https://support.einscan.com/en/support/home) to view product introduction and other operations.

Settings

Function	Description
User Experience	To help us improve the quality and user experience of the device, we hope to be allowed to collect usage experience information. This information will not contain your personal information or scanned data and will not be accessible to any third party.
Factory Default	All settings can be restored to the initial settings, and the software will automatically restart.
Language	Select another language here.
About	View related software release information, contact information, etc.

Help

Function	Description
Calibration Guide	Checked by default, will display video guide in calibration.
User Manual	Open a browser to show user manual.
Teamviewer	The quick access to remote assistance. Send the ID and password in the pop-up window to the technical supporters for remote assistance.

Other component

Component	Description
Camera Windows	This is the camera window in scan process. Show one by default, you can open other camera windows through Right-click menu.
Project Group Project Group	Here you can manage your project group, for more detail please refer to Project and project group .
Scan Setting Brightness Working distance(mm) 400	Here you can set the parameter when scanning, for more detail please refer to Scan Setting.

Component	Description
Project Information Project Information: Object Features 0.5mm Texture Remaining memory: 70% CPU usage:23% GPU usage:4%	In this area, you can check the project information and computer information.
Working distance indicator	Indicate working distance between the scanner and the object. Green: proper Red: too close Blue: too far
Edit	Please refer to Data edit.
Sidebar	Please refer to Scan function.

Quick guide

- 1. Create a project group, setup project settings.
- 2. Set scan parameters while preview .
- 3. Scan and generate point cloud.
- 4. Mesh.
- 5. Save the scan data.

Calibration

With **calibration**, the scanner parameters are recalculated, which not only ensures the accuracy of the scanner, but also improve the quality of scanning.

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Note

Calibration is required under the following conditions:

- When the scanner is used for the first time.
- The scanner was severely shaken or shocked, such as shocked during transportation.
- Severe accuracy reduction, such as frequent errors in alignment or unrecognized markers.
- Incomplete data is acquired during the scanning or serious deterioration of the quality of scanned data.
- When the scanner is NOT calibrated more than 14 days, the software will prompt you to do calibration.

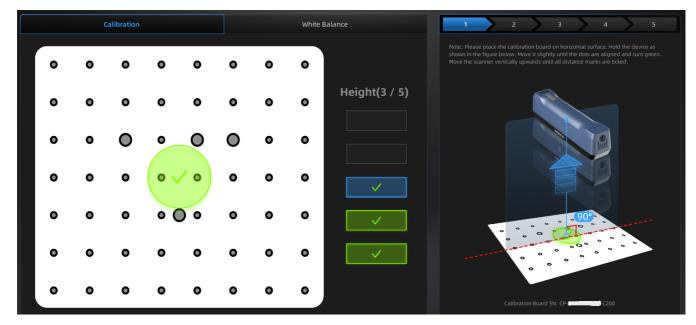
Warning

- The calibration board is matched to the device. Doing the calibration with an incorrect calibration board will fail to generate good scan data or optimum accuracy.
- Always make sure that both sides of the calibration board are clean and free of scratches.
- Do not place heavy objects or sundries on the calibration board.
- Keep the calibration board away from corrosives, metals and sharp objects to avoid corrosion or damage.
- It is not recommended to wipe the calibration board. When cleaning the board becomes very necessary, gently wipe it with a piece of a clean damp cloth. Do not use a cloth with chemicals or alcohols to wipe the calibration board.
- After using the calibration board, put it in a flannel bag.

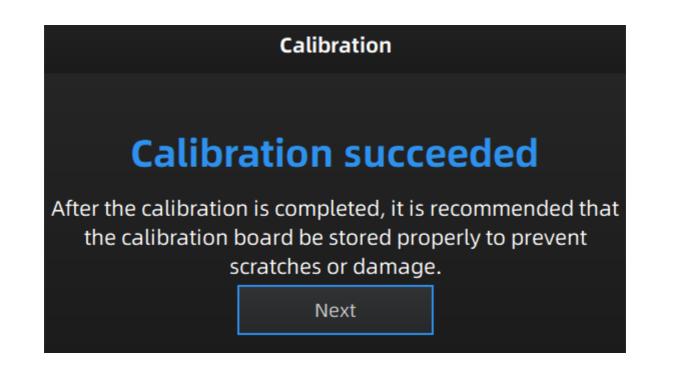
Steps

Follow the steps of the calibration wizard in the software. You need to calibrate the scanner from 5 different directions.

- 1. Place the calibration board horizontally, with its front site (white with markers) lying towards up.
- 2. Place the scanner in the same position as shown in the software.
- 3. Press the scan button on the scanner to start calibration.
- 4. Move the device slowly and adjust the distance between the scanner and the calibration board according to the height indicating box.



- 5. Keep moving until all height boxes turn green.
- 6. Place the scanner in the next position and repeat step3 to step5.
- 7. Check the calibration result.



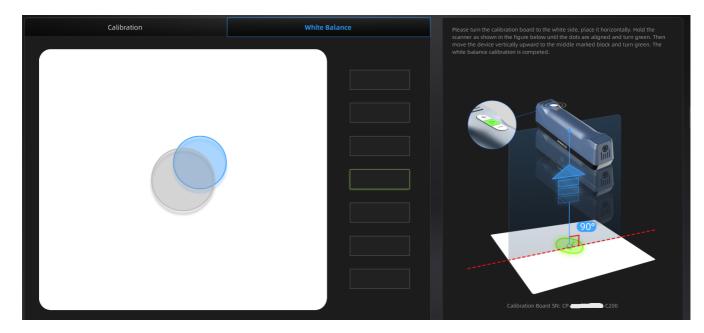
Note

- If the calibration fails, please try it again from step1.
- If you cannot get the pass result anyway, please contact your supplier or our support team (https://support.einstar.com/).

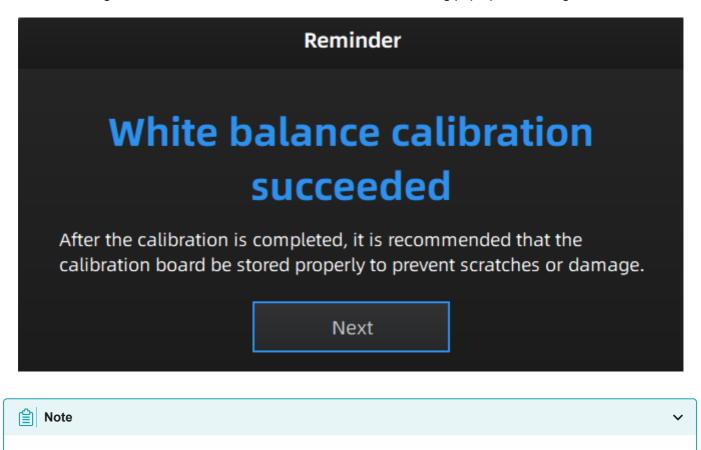
White balance

Steps

- 1. Place the calibration board on a horizontal flat surface with its back site (white) lying towards up.
- 2. Hold the scanner face to the center of board in upright position.
- 3. Press the scan button on the scanner to start calibration.
- 4. Keep moving the scanner up and down slowly until the scanner takes a photo automatically, which indicates that the distance is optimal.



5. After finishing the white balance calibration, click Next on the following pop-up for entering the scan mode.



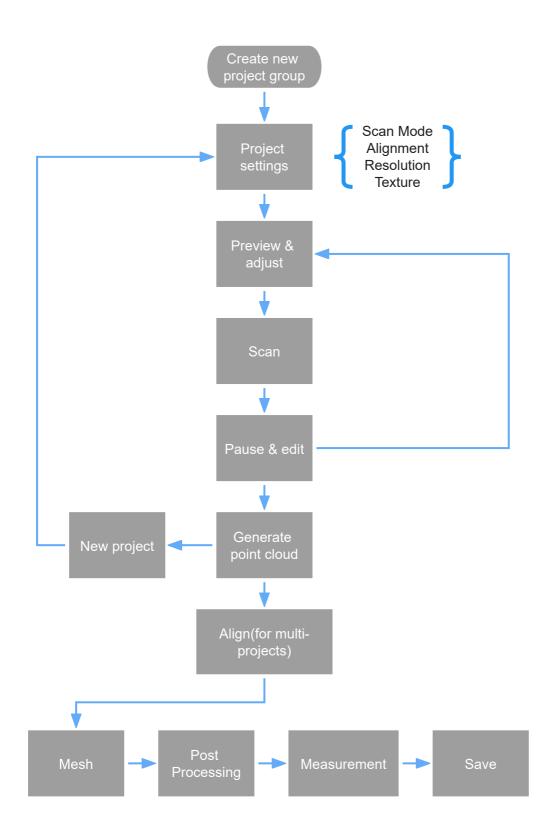
- Do not do white balance or scan under strong light, it may cause color deviation.
- If white balance fails, please try it again.
- If you cannot get the pass result anyway, please contact your supplier or our support team (https://support.einstar.com/).

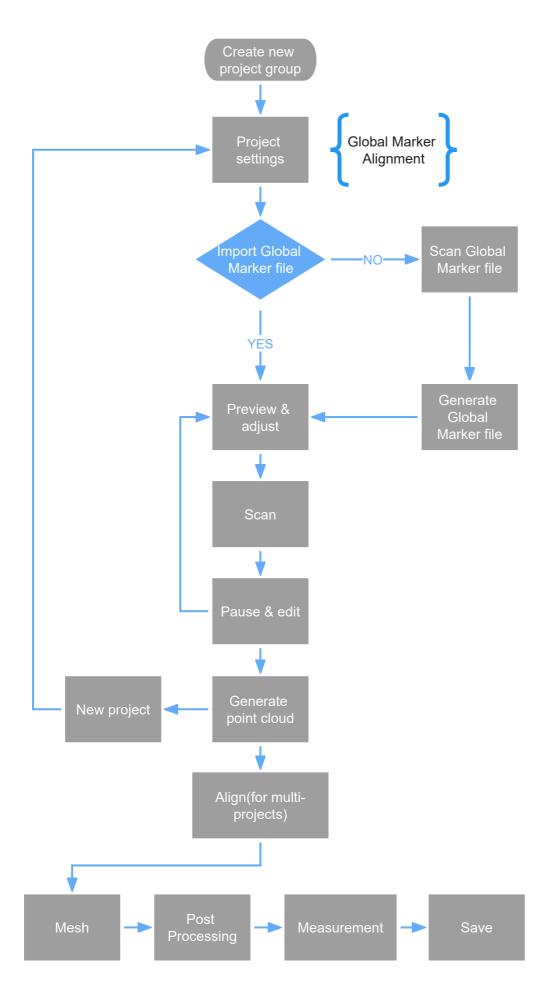
Scan

Workflow

Below is the workflow of the scanner. There are two different workflows: Basic workflow, Global marker workflow.

The basic workflow can fulfill most of your needs, if you want higher accuracy, you can use global marker workflow.





Preparation

Object has good geometry or texture features will get scanned easily and fast with good quality. If not, you need to do some preparation before scanning.

Note

Not recommend to scan following objects:

- Moving or vibrating objects, which cause the shape of object changed during scanning process.
- Soft material object.
- Lattice structures with many small deep holes.

Preparation for portrait scan

Hair



Bad sample

Good sample

V

Preparation for different object

Object	Preparation	Notes while scanning
Transparent, shiny, reflective surface objects	Use washable or vanishing scanning spray	Scan as normal
Objects with less features or repetitive features	- Place markers on the object. - Mark/draw on the surface to add features	- Select hybrid alignment. - Select texture alignment
Thin wall objects	Place markers on and around the objects	Choose global marker alignment

Project and project group

Project group

To start scanning, you need to create / open a **project group**. Project group is the standard file structure of the software, it contains one project or more. Each project contains the scan data of its own.

Scenario	Project group	Instruction
One object in the scene, one align mode for the object	One project in the group	Only need one project to finish the scan
Multiple objects in the scene, all can align with the same mode	One project in the group	only need one project to finish the scan
Multiple objects in the scene, need different align mode	One project for each object	The objects might be different in material or need different align mode
A big object in the scene	One project for one part of the object	Scan different part and align together
One object in the scene but needs different align mode in different part	One project for each part of the object	Scan different part and align with different mode

Create project group

Two ways to create a project group:



- 1. Before scanning, click **scan** in navigation bar, then click **new project group** in prompt.
- 2. In **scan** window, click **project group** in side bar, then click **new project group** in prompt.

In the prompt window, name the project group and **new** to the path you choose, all the scan data will be saved to the folder with the name you just set.

Open project group

Note Current project group will be saved automatically.

Two ways to open a project group:

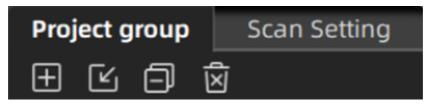
- 1. Before scanning, click **scan** in navigation bar, then click **open project group** in prompt.
- 2. In scan window, click project group in side bar, then click open project group in prompt.

In the prompt window, select the project group file and then open.



Project

Consider each **project** as a part of the **project group**. All operations of project can be done by the following buttons.



icon	function	instruction	note & warning
Đ	Create new project	 Two ways to create a project: 1. A project will be created automatically when you create a project group. 2. In scan window, click to create a new project. 	Only can create project when scanner connected.
	Open project	 Two ways to open project: 1. When opening a project group, all project(s) of this group will be loaded to the software. 2. Click to open the project of one project group. 	Cannot open project with different resolution or texture setting.
Ð	Remove project	Click to remove selected project from the project tree.	The data will not be deleted, you can open the project when needed.
۱	Delete project	Click to delete the project from the project tree, and delete all the data of this project.	This operation will delete the scan data from the computer permanently.

Project setting

Einstar support two scan modes: Portrait scan, Object scan.



You need to choose scan mode when you create the project. With different scan mode, the settings below will be different.



Alignment

Scan Mode	Alignment	Instruction
Portrait Scan	- Features - Texture - Hybrid	Hybrid alignment here means feature alignment plus texture alignment.
Object Scan	- Features - Texture - Hybrid - Global Markers	 When select Global Markers alignment, if global marker file not import, you need to scan global marker file first. Hybrid alignment here means feature alignment plus marker alignment. Small object scan not support Global Markers alignment.

Note

FEATURE ALIGNMENT uses object geometric features for auto aligning during scanning. Rich features on the object are required for this mode.

TEXTURE ALIGNMENT uses objects surface texture to align the scans. Texture Scan is required to select if you want to use texture align.

GLOBAL MARKERS ALIGNMENT uses global markers file to help align the scans. You may add a existed global markers file or scan one.

HYBRID ALIGNMENT uses features, texture or markers to align the scans. Use the function to avoid alignment error in some target parts. By this alignment, we don't need to place the markers all over the part, but only on the region where has less geometry.

Resolution

Scan Mode	Resolution	Default Value
Portrait Scan	0.2mm~3.0mm	1.0mm
Object Scan	0.2mm~3.0mm 0.1mm~0.5mm(Small object)	0.5mm 0.2mm(Small object)

Note

- With smaller setting value, you will get more detail, but will lead to larger file size and longer processing time.
- Resolution cannot be changed once the project group been created.

Texture

Texture	lcon	Instruction
Texture on		will capture texture data
Texture off	\bigcirc	will not capture texture data

Note	
Texture switch cannot be changed once the project group been created.	

1. Object size larger than 200mm X 200mm X 200mm. ←

2. Object size between 100mm X 100mm X 100mm and 200mm X 200mm X 200mm. -

Scanning Scan setting

Following parameters can be set when scanning.

Brightness

Adjust the brightness for different material / color of the object to get better scan data.



Working distance

Use short working distance to get more detail, but need more time to scan the whole object.

Use long working distance to get large FOV, scan time will be shorter, but will lose some detail of the data.

Scan Mode	Minimum distance	Maximum distance	Working distance range
Portrait	160mm	1400mm	>=200mm
Object	160mm	600mm 250mm(Small Object)	>=200mm >=40mm(Small Object)

Other function

Function	Value	Instruction
Data Quality Indicator	ON/OFF	To indicate the data quality of your scan, help you to get better scan data. - Only available before generating point cloud.
Texture LED Light	ON/OFF	Please turn on the LED light when there is not enough light for better texture scanning (This function is enabled by default). - Only available when texture on - Cannot change during scanning
Hair Mode	ON/OFF	Easier to scan hair, but also increase data noise. - Only available in Portrait Scan mode. - Cannot change during scanning.

Scanning

Preview / Scan / Pause

You can always switch in these 3 status with the trigger on the scanner, or click the button in the software. The basic switch order is: **Preview -- Scan -- Pause**

Function	lcon	Instruction
Preview	₽	In this mode, only show data for preview, but not record the data, you can modify the scan parameters according to the preview.
Scan	\triangleright	Start scanning, data is recorded. During scanning, make sure to keep the scanner perpendicular to the surface, keep a proper distance from the object, and adjust the brightness depending on the ambient light or texture of the object.
Pause	00	Pause scanning, you can <mark>edit the scan data or change the view angle</mark> if you want.



Preview

Generate point cloud

When you finish the scan, you can **Generate Point Cloud**¹ or **Optimize and Generate Point Cloud**². You may want to edit the data later.

Note
The time it takes to generate point cloud depends on the data size of your project and the hardware configuration of your PC.

- 1. To generate point cloud directly without any optimization, will be fast and less memory been used; Only available in **Object Scan.** ←
- 2. Optimize then generate point cloud, suggest choosing this option when you have higher accuracy requirement or when there is layering problem caused by accumulated aligning errors during scanning. ←

Scan data edit

We provid functions to edit the scan data when you pause scanning or after you generate point cloud.



lcon	Function	Instruction
ď	Multi View	There are 6 different view angles for you to choose.
	Create Cutting Plane	Create a plane to do quick cut, check below for detail.

lcon	Function	Instruction
[]]	Rectangular	Click and hold LMB to drag to select / deselect an area of the data.
1-1	Polygon	Click LMB one-by-one to select / deselect an area of the data.
\mathbf{Q}	Lasso	Click and hold LMB to drag to select / deselect an area of the data.
/	Straight Line	Drag to create a line to select / deselect an area of the data.
\triangleleft	Brush	Use brush to select / deselect an area of the data.

lcon	Function	Instruction
	Select All	Select all of the data.
[x]	Unselect	Cancel all the selections.
	Connected Domain	Click the button after select data, all connected region to the selected data will be picked.
	Revert	Revert the selection.
	Delete	Click the button or "DELETE" on the keyboard to delete selected data.

lcon	Function	Instruction
5	Undo	Click the button to undo the most recently operations.
\times	Cancel	Undo all edit, and exit edit mode.
\checkmark	Apply	Click the button or space bar to apply the edit, and exit edit mode.



Cutting plane

Cutting plane is very useful when a base needs to be removed during scanning.

After setting cutting plane, there will be no more data scanned below the cutting plane.

Create cutting plane

Three methods to create cutting plane:

Method	Instruction
Fitting Point Cloud	Press Shift + LMB to select data, then click the button "Generate plane". The cutting plane will be created by point cloud fitting. The direction of the plane will be calculated by the software according to the direction of point cloud.
Creating Straight Line	Press Shift + LMB to draw a line, and generate the cutting plane according to the line.
By Markers	Press Shift + LMB to select markers. 3 markers or more are required to generate the cutting plane.

Set cutting plane

Method	Instruction
Rotation axis	Cutting plane can be rotated around the axis by operating the active bar, editing the text box or placing the cursor on the edge of the cutting plane and dragging.
Move cutting plane	Move the cutting plane by operating the active bar, editing the text box or placing the cursor in the center of the cutting plane and dragging.
Delete	Click this option, data in the reverse direction will be shown in red. Apply this, and the red data will be deleted.
Reverse	Reverse the normal direction of the cutting plane.
Delete plane	Delete the created cutting plane.

Scan functions

Before or after scanning, you can access the other scan functions through the sidebar function buttons.

lcon	Function	Instruction
	Project Group	Create / open a project group. About project group, please refer to <mark>Project Group</mark> .
	Clean Data	Clean the current point cloud data to redo scan.
£ 3	Align	Align the data as you need, please refer to Align.
6	Save Data	Save scan data.
0	Show Texture	To show / hide texture on screen.
*	Mesh	Will move to next step "Post Processing" to mesh.

Align point cloud

This is how you align multiple projects in one project group.

Click on the right side of the interface to enter the project alignment interface.

Align Mode	Instruction	Note
\Diamond	Choose Feature Alignment and click Apply , alignment will be performed automatically.	Regular shaped objects (circular objects and square objects included) or small sized objects are not suitable for this mode.
Ì	Manually choose at least 3 common points in the fixed window and floated window. Click Apply to align.	 The chosen points should NOT in a line. Manual alignment is a supplement to feature alignment, which can solve the problem of feature alignment failures such as some areas with few common areas or extremely similar areas. The data is aligned by the best fit of all points of the data in the floated viewport and the fixed viewport.
	If the currently selected project is a marker project, the marker alignment can be performed. The software will automatically align according to the mark points.	The two projects have no less than 3 common markers each other.
Ċ)	Select two project files and manually select multiple (≥3) markers for alignment.	 The selection of markers should be as separate and random as possible. The selected markers will be cleared after aligning.

Note

You should generate point cloud before doing align.

Post processing

Mesh

Meshing is to convert the point cloud into a triangular mesh surface. The data after mesh can be directly used for rendering, measurement or printing.

Mesh type

lcon	Function	Instruction
	Unwatertight	Unclosed model stays the way it is scanned. Processing time is quicker than Watertight.
	Half watertight	Some of the holes will be filled automatically.
	Watertight	All holes will be filled automatically. The data can directly be 3D printed.

Note			

- Half watertight mesh: Holes with a diameter less than or equal to the *resolution* x 5 will be filled.
- Watertight mesh: Only in watertight mesh can set model quality.

Mesh optimization

Optimization	Instruction	Note
Filter	Optimize the data and improve the clarity of the data. The higher the level, the less the small details . Filter None Low Med High	 None: No optimization Low: Optimizes data slightly and preserves data characteristics Med: Reduce the noise on the surface of the scan data High: Reduce the noise on the surface of the scan data and sharpen it powerfully.
Smooth	Smooth the possible noise on the surface of the scan data. Smooth Low Med High	
Remove small floating parts	Remove small floating parts on the model. Remove Small Floating Parts 1	
Simplification	Select to reduce the polygon numbers, file size and detail of data while meshing.	 Resolution <= 0.5mm, simplification will be selected by default. Resolution > 0.5mm, simplification will be deselected by default.
Max triangles	Set max plate number to get mesh model's triangle plate number is within configured plate number. Max triangles ① 20000000	
Fill small hole	Auto fill the small hole when mesh. Fill Small Hole Small Hole Perimeter(mm)	Default value 10mm, for objects with holes (smaller than 10 mm), please set the function parameter value to a smaller one.

Optimization	Instruction	Note
Remove spike	Remove spike-like data on the image edge.	
Marker hole fill	Fill in the surface of the object that is not scanned to the pasting marker.	

Click **Apply** to confirm the settings and start meshing, you can click **Confirm** to confirm the mesh result. Click **Cancel** to restore and exit the function.

Mesh editing

Left panel

Click + to open each function.

Function	Instruction	Note
Texture	Brightness and Contrast can be adjusted.	Confirm to apply, Cancel to restore
Simplification	After simplification, the polygon numbers, file size and detail of data will be reduced universally.	High level may cause detail loss. Set the ratio from 1 to 100, the default is 0.
Mesh Optimization	Mesh optimization can optimize the quality of the data by adding more triangles to curvature regions.	
Smooth	Smooth the possible noise on the surface of the scan data.	It might remove some small details or smooth some sharp edges at the same time. Set the ratio from 1 to 100, the default is 0.
Remove small floating parts	Remove small floating parts in the scan data.	From 0 to 100% where 100% is the size of the largest mesh island. Smaller islands will be removed. 0 means no operation, 100 is the maximum. The maximum value is the square of the diagonal length of the floating part/10, MAX=(L/10) ² .
Auto Hole Filling	Auto fill every hole with a smaller perimeter than the number input. Hole France Tangent Flat	 Choose Curvature, Tangent or Flat before filling hole. FLAT: calculates the solution for the hole filling considering the point position on the boundary. TANGENT: calculates the solution considering the point position and the normal of the last row of triangles forming the boundary. CURVATURE: calculates the solution considering the point position and the normal of the 2 last rows of triangles forming the boundary.
Manual Hole Filling	The hole edges are displayed green and get red after picking. The number of the holes and the number of holes filled will be displayed on the interface.	Choose Curvature, Tangent or Flat before picking a hole.

Function	Instruction	Note
Flip Normal	To redefine the front direction of the scanned data in reversal design.	Texture mapping will be unavailable after flip Normal
Cutting Plane Tool	Define a plane by drawing a straight line. Delete the selection and close the mesh at the intersection. Use the cutting plane to align the mesh to the CSYS.	
Mirror	Mirror the mesh through a plane defined by a straight line.	After mirroring, texture remapping cannot be performed.

Bottom panel



lcon	Function	Instruction
\otimes	Select Visible	To select data on the front view only.
\otimes	Select through	To select data all through.

🖹 Note

The other editing functions are the same as point cloud editing

Right panel

lcon	Function	Instruction
	Open file	Open a file (STL, OBJ, PLY) for post processing
Γο	Save Data	Save scan data.
	Sketchfab Upload	Use your Sketchfab (http://sketchfab.com) account to share the model.
$\mathbf{\hat{Y}}$	Third-party software	Save the data and open with third-party software.
\overleftrightarrow	Texture remapping	After the post-processing, hole filling on texture scanned data will affect the texture render. By doing the texture remapping, the texture information will be reapplied on the mesh.
\bigcirc	Show Texture	To show / hide texture on screen.

Measurement

You can measure on the model you just scanned, or you can open a model file to do the measurement, the software supports .stl, .obj, .ply files.

Create features

To use **3-2-1 System Movement**, you need to create features first. There are three kinds of features you can create: point, line and plane.

Point

Two methods to create a point: **Selected Points**, **Line-Plane Intersection**. You can select different method from drop-down menu.

Creation Method	Requirement	Description
Selected Points	-	1, click on the data to select a point. 2, click Create to create a point. 3, repeat 1 and 2 to create more points.
Line-Plane Intersection	 line and Plane should be created in advanced. line should not be parallel to the plane. 	 click on the created line, or select it on the drop- down. click on the created plane, or select it on the drop- down. the point generated is the intersection between the non-parallel line and plane.

Line

Two methods to create a line: Point-Point, Plane-Plane Intersection.

Creation Method	Requirement	Description
Point-Point	need 2 points	 click on the model to create a point, or select a created point as the line starting point. click or select another point as the line ending point. click Create to create the line.
Plane-Plane Intersection	- 2 planes should be created in advanced. - planes should not be parallel.	 click on the plane previously created, or select it from the drop-down menu. repeat for the second plane. The created line is the intersection between the 2 non-parallel planes.

Plane

Three methods to create a plane: 3 Points Fit, Point-Line Fit, Best Fit.

Creation Method	Requirement	Description
3 Points Fit	3 points are not collinear.	 click on the model to create a point, or select a created point from drop-down menu. repeat to create two other points. click Create to create a plane.
Point-Line Fit	 line should be created in advanced. point should not lie on the line. 	1, select a line created. 2, create or select a point. 3, click Create to create the plane.
Best Fit	-	 press Shift + LMB to select an area, press ctrl + LMB to deselect. click Create to create the plane best fit for the area which you just selected.

Movement

Use this mode to modify the alignment of the data to the global coordinate. This action is useful for post processing or reverse engineering.

The transformations do not affect the shape and size.

Exact Movement 3-2-1System Movement Offset to	Exact Movement 3-2-1System Movement
x _10	Method
Offset to	Plane plane2 V Method X+ V
Rotate to x 0 0 y 0 0 z 0 0 Rotate to	Line Constraint Line V Method Select V Point Constraint Point V
Reset Close	Align Reset Close

Movement method	Description	Steps
Exact Movement	 Offset: adjust the object data center coordinates in X, Y, Z axis. Rotation: adjust the rotation angle in X, Y, and Z axis. 	 Enter the setting value then click Offset or Rotate. Repeat step 1 until it meets your needs. Click Close to save the results and exit. Click Reset to cancel all movement.
3-2-1 System Movement	3-2-1 system movement aligns model by selecting the point, line and plane. Before movement, create feature points, lines and planes. The feature lines created are not perpendicular to the plane. The coordinate system on the interface represents the global coordinate system. Red=X+, Green=Y+, Blue=Z+.	 Make a one-to-one correspondence between the created feature points, lines and planes with the origin and axis of the coordinate system to be aligned. That is, the normal of the selected plane corresponds to the coordinate axis; the selected feature point corresponds to the origin. Select a feature plane in the plane drop-down menu, and select an axis in the corresponding constraint drop-down menu of the plane. The arrow on the plane corner indicates the positive direction of the plane, and the selected axis direction will be consistent with the plane direction. Select a feature line in the drop-down menu of the line, and select an axis in the drop-down menu of the line. The arrow of the line indicates the positive direction axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the selected axis will be consistent with the direction of the projection of the line on the selected plane. Click the drop-down menu to select a point, the position of this point is the origin of the coordinates (0, 0, 0).

Measure

Three kind of measurements can be done in the software: **Distance**, **Surface area** and **Volume**.

Measurement	Description	Steps
Distance	Calculates the distance between two points on the surface of the model.	Click on the surface of the model to pick two points, the calculation will be done automatically. - Total is the 3D distance, X , Y and Z are the projection of the segment to the respective planes.
Surface area	Calculate the surface area value.	 Press Shift + LMB to select an area, press Ctrl + LMB to unselect. Ctrl + A to select all. Click Calculate to display the Area value of the selected data in mm².
Volume	Calculate the volume contains in a watertight mesh.	It returns the volume in mm³ and the coordinates of the bounding box. - Only available for watertight mesh.